

Recall:

$$f: \mathbb{R} \rightarrow \mathbb{R}$$

$$y = f(x)$$

Single variable calculus.

$$\lim_{x \rightarrow c} f(x), f'(x)$$

$$\int_a^b f(x) dx$$

$$f: \mathbb{R} \rightarrow \mathbb{R}^m \text{ (curves in } \mathbb{R}^m \text{)}$$

$$f(t) = (x_1(t), \dots, x_m(t))$$

today

$$F: \mathbb{R}^n \rightarrow \mathbb{R} \text{ (multivariable function)}$$

$$F(x_1, \dots, x_n) \in \mathbb{R}$$

$$F: \mathbb{R}^n \rightarrow \mathbb{R}^m \text{ (most general).}$$

Curves in \mathbb{R}^m

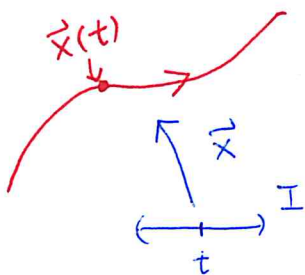
Defⁿ: Let $I \subset \mathbb{R}$ be an interval.

A curve in \mathbb{R}^m is a (vector-valued) function

$$\vec{x}: I \rightarrow \mathbb{R}^m$$

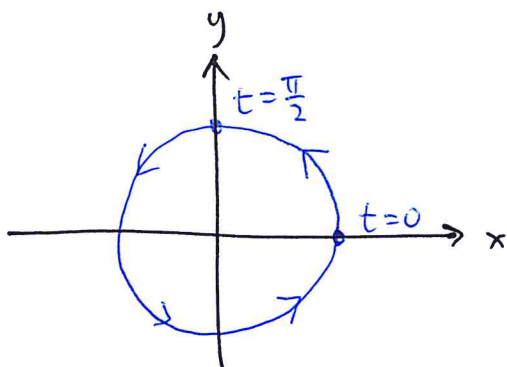
$$\vec{x}(t) = (x_1(t), \dots, x_m(t)) \quad t \in I.$$

Component functions.

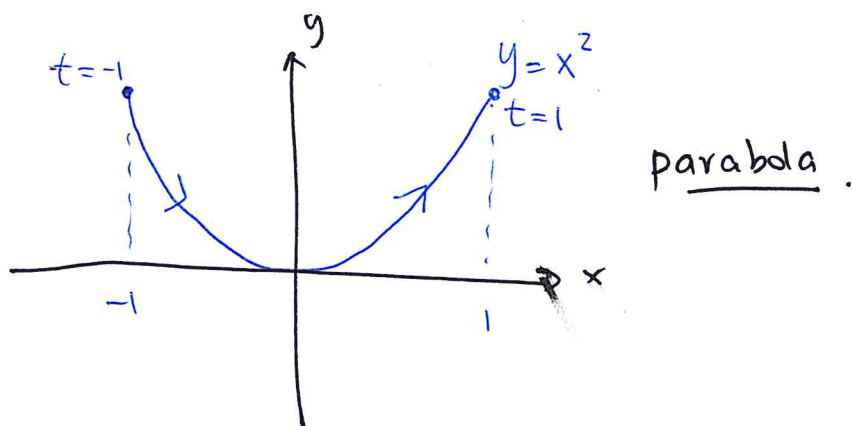


Examples:

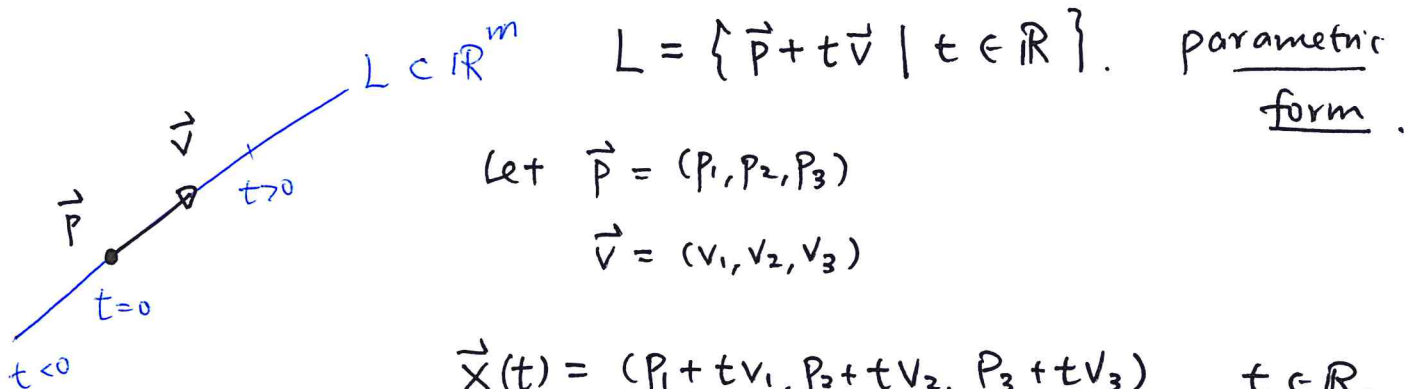
(1) $\vec{x}(t) = (\cos t, \sin t), t \in \mathbb{R}$



(2) $\vec{X}(t) = (t, t^2)$, $t \in [-1, 1]$.



Remark: A curve is the geometric object together with a "parametrization".



Let $\vec{P} = (P_1, P_2, P_3)$

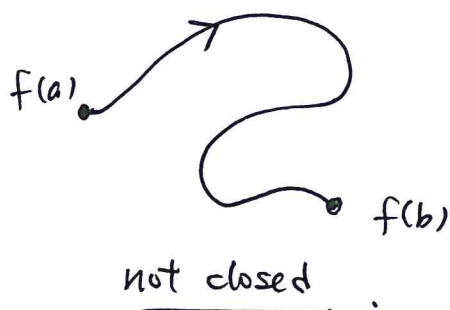
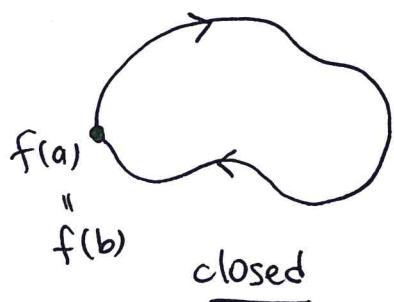
$\vec{v} = (v_1, v_2, v_3)$

$\vec{X}(t) = (P_1 + tv_1, P_2 + tv_2, P_3 + tv_3)$ $t \in \mathbb{R}$.

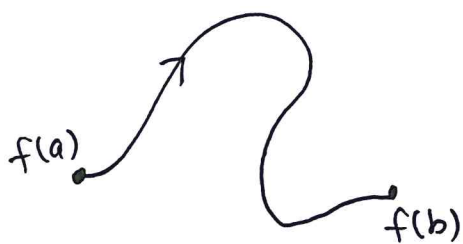
$\vec{y}(t) = (P_1 + 2tv_1, P_2 + 2tv_2, P_3 + 2tv_3)$ $t \in \mathbb{R}$.

different parametrization of the same line.

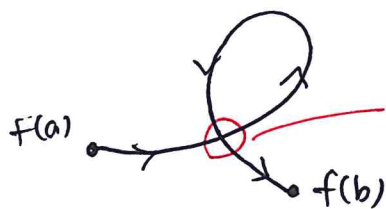
Closed Curves: Def: $f: [a, b] \rightarrow \mathbb{R}^m$ is closed if $f(a) = f(b)$



Simple curves: Defⁿ: $f: [a, b] \rightarrow \mathbb{R}^m$ is simple if f is 1-1 on (a, b) .



Simple



crossing / self-intersection.

not simple

Analytic Properties

Let $\vec{x}: I \rightarrow \mathbb{R}^m$, $t_0 \in I$.

limit: $\lim_{t \rightarrow t_0} \vec{x}(t)$

derivative: $\vec{x}'(t)$

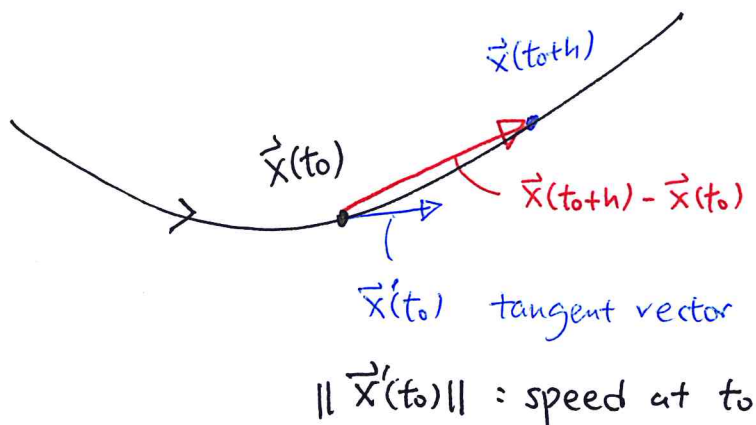
if $\vec{x}(t) = (x_1(t), \dots, x_m(t))$, then

$$\lim_{t \rightarrow t_0} \vec{x}(t) = \left(\lim_{t \rightarrow t_0} x_1(t), \dots, \lim_{t \rightarrow t_0} x_m(t) \right)$$

if they exist

$$\vec{x}'(t_0) = \left(x_1'(t_0), \dots, x_m'(t_0) \right) = \lim_{h \rightarrow 0} \frac{\vec{x}(t_0+h) - \vec{x}(t_0)}{h}$$

Picture:



Physics:

$\vec{x}'(t_0)$: velocity.

$\vec{x}''(t_0)$: acceleration

$$\boxed{F = ma}$$

\Downarrow

$$\boxed{\vec{F} = m \vec{x}''}$$

Arc length: $\vec{x}: [a, b] \rightarrow \mathbb{R}^m$

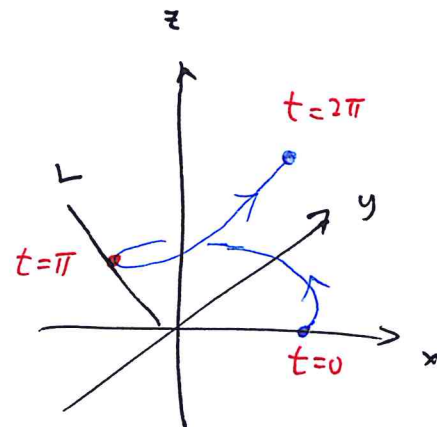
$$\text{arc length} := \int_a^b \|\vec{x}'(t)\| dt.$$

Example (Helix)

$$\vec{x}(t) = (\cos t, \sin t, t), \quad t \in [0, 2\pi]$$

Find (a) the tangent line at $t = \pi$

(b) arc length of the helix.



Sol: (a) At $t = \pi$,

$$\vec{p} = \vec{x}(\pi) = (-1, 0, \pi)$$

$$\vec{x}'(t) = (-\sin t, \cos t, 1)$$

$$\vec{x}'(\pi) = (0, -1, 1) = \vec{v}$$

$$L = \{ (-1, 0, \pi) + t(0, -1, 1) \mid t \in \mathbb{R} \} \quad \text{tangent line at } t = \pi.$$

$$(b) \|\vec{x}'(t)\| = \sqrt{(-\sin t)^2 + (\cos t)^2 + 1^2} = \sqrt{2}$$

$$\text{arc length} = \int_0^{2\pi} \|\vec{x}'(t)\| dt = \int_0^{2\pi} \sqrt{2} dt = 2\sqrt{2}\pi \quad *$$

Diff. Rules:

$$(1) [\vec{x}(t) \pm \vec{y}(t)]' = \vec{x}'(t) \pm \vec{y}'(t)$$

$$(2) [c\vec{x}(t)]' = c\vec{x}'(t)$$

$$(3) [f(t)\vec{x}(t)]' = f'(t)\vec{x}(t) + f(t)\vec{x}'(t)$$

$$(4) [\vec{x}(t) \cdot \vec{y}(t)]' = \vec{x}'(t) \cdot \vec{y}(t) + \vec{x}(t) \cdot \vec{y}'(t)$$

$$\underline{m=3} \quad (5) [\vec{x}(t) \times \vec{y}(t)]' = \vec{x}'(t) \times \vec{y}(t) + \vec{x}(t) \times \vec{y}'(t)$$

} product rules.

Q: Prove these!

Last time ... $\vec{x}: I \subset \mathbb{R} \longrightarrow \mathbb{R}^m$

$$\vec{x}(t) = (x_1(t), \dots, x_m(t))$$

Basic Point Set Topology ($\Omega \subset \mathbb{R}^n$)

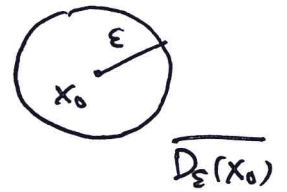
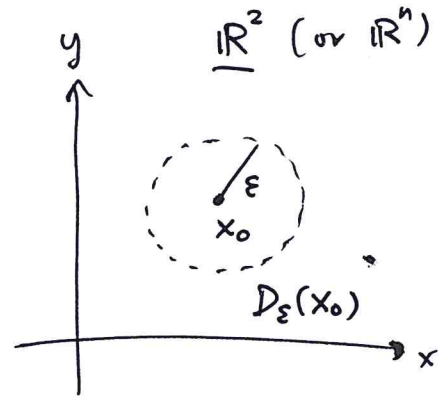
In \mathbb{R}^n , denote.

$$D_\varepsilon(x_0) := \{ x \in \mathbb{R}^n \mid \|x - x_0\| < \varepsilon \}$$

↑ open ball with radius ε and center at x_0

$$\overline{D}_\varepsilon(x_0) := \{ x \in \mathbb{R}^n \mid \|x - x_0\| \leq \varepsilon \}$$

closed ball with radius ε , center at x_0

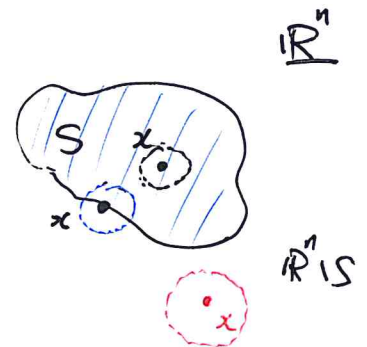


• If $S \subset \mathbb{R}^n$, we can classify $x \in \mathbb{R}^n$ into one of the following types

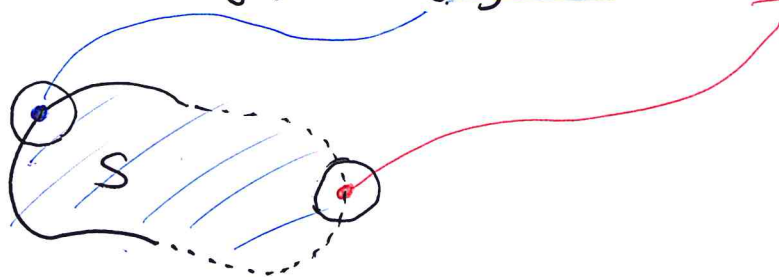
(1) interior points: $D_\varepsilon(x) \subset S$ for some $\varepsilon > 0$

(2) exterior points: $D_\varepsilon(x) \subset \mathbb{R}^n \setminus S$ for some $\varepsilon > 0$

(3) boundary points: $D_\varepsilon(x) \cap S \neq \emptyset$
 $D_\varepsilon(x) \cap (\mathbb{R}^n \setminus S) \neq \emptyset$ for all $\varepsilon > 0$



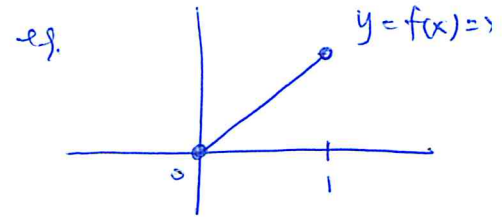
Remark: We may have boundary points lying in S or not in S.



Denote: $\partial S := \{ x \in \mathbb{R}^n \mid x \text{ is a boundary point of } S \}$.

Generalize: (a, b) open interval \rightarrow derivative.

$[a, b]$ closed interval \rightarrow optimization
min/max $f(x)$

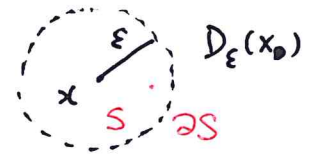


Defⁿ: Let $S \subset \mathbb{R}^n$.

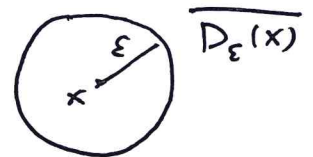
(i) S is open: $\partial S \subset \mathbb{R}^n \setminus S$

ie. $\forall x_0 \in S, \exists \epsilon > 0$ st. $D_\epsilon(x_0) \subset S$.

[Remark] \nearrow depends on the point x_0



(ii) S is closed: $\partial S \subset S$.



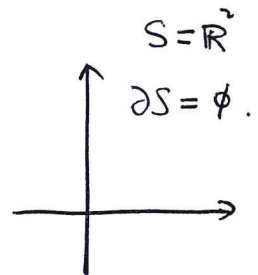
Ex: S is closed $\Leftrightarrow \mathbb{R}^n \setminus S$ is open.

Remark: Some sets are not open nor closed.

e.g. $(a, b]$

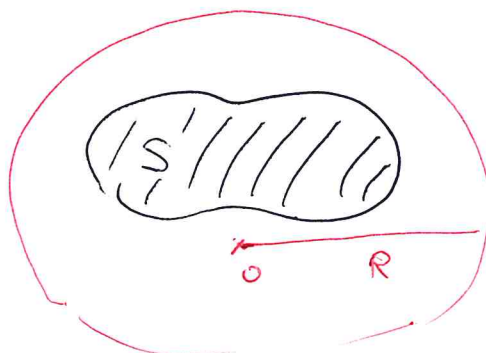
Some sets are both open and closed in \mathbb{R}^n .

only two cases: $S = \emptyset$ and \mathbb{R}^n



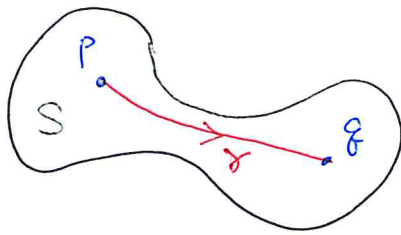
Defⁿ: (1) $S \subset \mathbb{R}^n$ is compact if S is closed and bounded.

$\hookrightarrow \exists R > 0$ large st. $S \subset D_R(0)$.

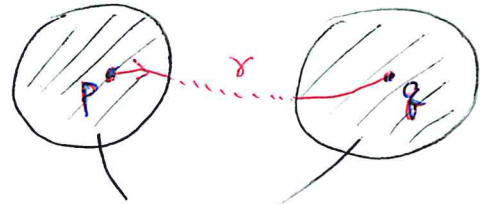


"Compact"
 \Updownarrow
"finiteness"

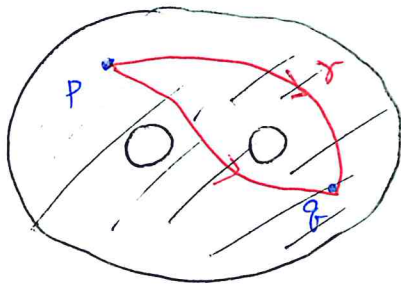
(2) $S \subset \mathbb{R}^n$ is connected if any two points $p, q \in S$ can be joined by a continuous curve γ inside S .



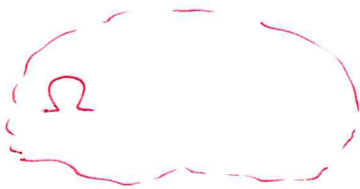
connected



not connected



(3) $\Omega \subset \mathbb{R}^n$ is domain if it is open & connected.



Continuity: $f: \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$, Ω : domain

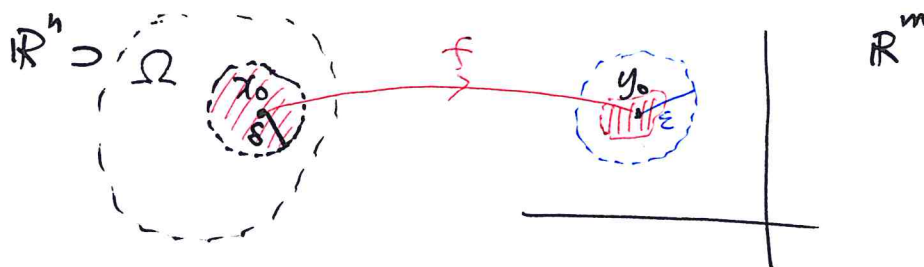
f is continuous \Leftrightarrow (i) $\forall x_0 \in \Omega$, $\lim_{x \rightarrow x_0} f(x) = f(x_0)$

i.e. $\forall \epsilon > 0$, $\exists \delta > 0$ st

$\|f(x) - f(x_0)\| < \epsilon$ if $\|x - x_0\| < \delta$.

\Leftrightarrow (ii) $\forall y_0 \in \mathbb{R}^m$, $\forall \epsilon > 0$,

$f^{-1}(D_\epsilon(y_0))$ is open.



Multivariable Function

$$F: \Omega \subset \mathbb{R}^n \longrightarrow \mathbb{R}^m \quad \Omega: \text{domain}$$

$$F(x_1, \dots, x_n) = (f_1(x_1, \dots, x_n), \dots, f_m(x_1, \dots, x_n))$$

component functions
of F .

Fact: $\lim_{x \rightarrow x_0} F(x) = \left(\lim_{x \rightarrow x_0} f_1(x), \dots, \lim_{x \rightarrow x_0} f_m(x) \right)$

\Rightarrow We just need to understand the case $m=1$

$$f: \Omega \subset \mathbb{R}^n \longrightarrow \mathbb{R} \quad \left(\begin{array}{l} \text{real-valued} \\ n \text{ indep. variables} \end{array} \right)$$
$$f = f(x_1, \dots, x_n)$$

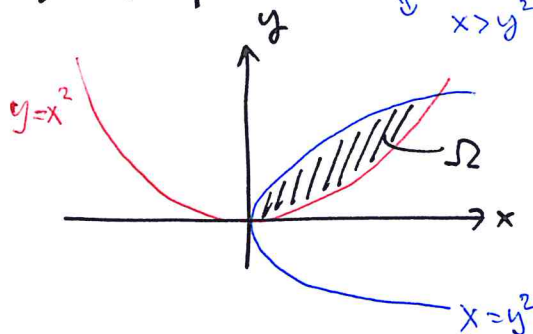
Example: $f(x, y) = x^2 - y^2$, $\Omega = \mathbb{R}^2$

$$F(x, y) = (\ln(x - y^2), \ln(y - x^2))$$

$$F: \Omega \subset \mathbb{R}^2 \longrightarrow \mathbb{R}^2$$

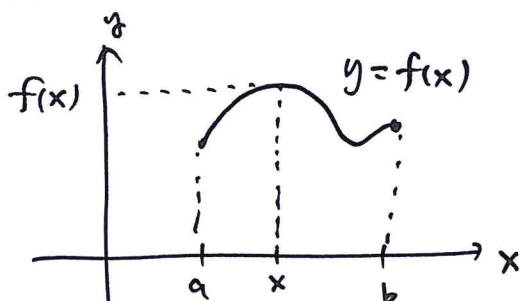
$$\Omega = \left\{ (x, y) \mid \begin{array}{l} x - y^2 > 0 \text{ and } y - x^2 > 0 \\ \Downarrow \quad \Downarrow \\ x > y^2 \quad \quad y > x^2 \end{array} \right\}$$

... $\ln x, x > 0$

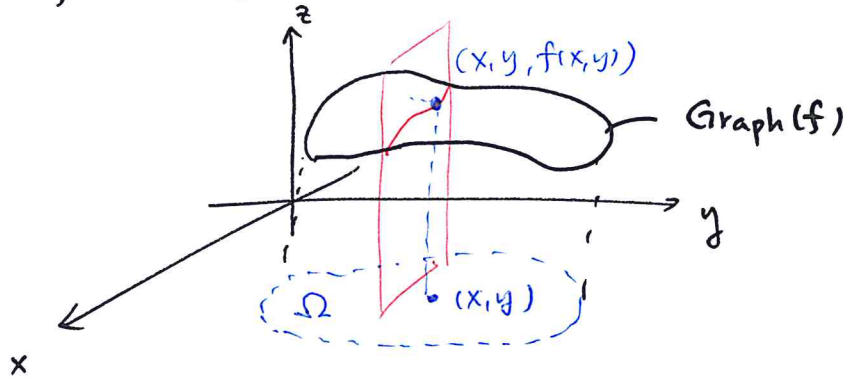


Q: How to understand $f(x_1, \dots, x_n)$?

Graph of f : $f: [a, b] \longrightarrow \mathbb{R}$



$$f = f(x, y) : \Omega \subset \mathbb{R}^2 \rightarrow \mathbb{R}$$



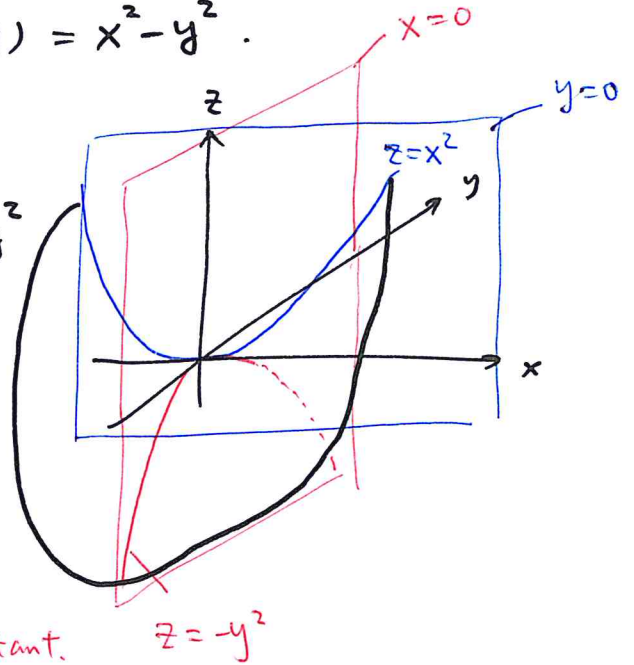
Defⁿ: If $f(x_1, \dots, x_n) : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$, then

$$\begin{aligned} \text{Graph}(f) &:= \left\{ (x_1, \dots, x_n, f(x_1, \dots, x_n)) \mid (x_1, \dots, x_n) \in \Omega \right\} \\ &= \left\{ (x_1, \dots, x_n, u) \mid \begin{array}{l} u = f(x_1, \dots, x_n) \\ (x_1, \dots, x_n) \in \Omega \end{array} \right\} \subset \mathbb{R}^{n+1} \end{aligned}$$

Example: Sketch the graph of $f(x, y) = x^2 - y^2$.

Idea of "slicing":

vertical $\left\{ \begin{array}{l} \text{Fix } x=0, \quad f(0, y) = -y^2 \\ \text{Fix } y=0, \quad f(x, 0) = x^2 \end{array} \right.$



Horizontal slicing:

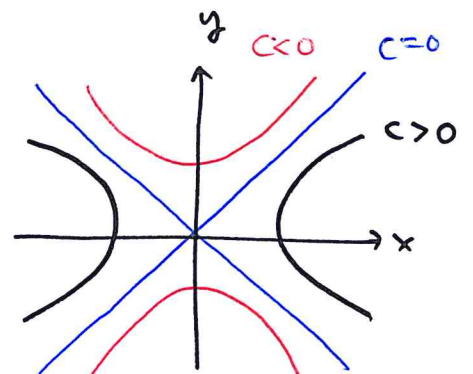
Slice by horizontal planes: $z = c$

Constant. $z = -y^2$

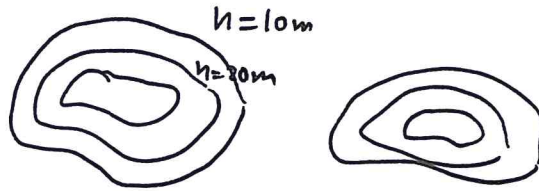
$$\begin{cases} z = f(x, y) \\ z = c \end{cases} \Rightarrow \boxed{f(x, y) = c}$$

contour/level curve.

$$\begin{aligned} x^2 - y^2 = 0 &\Rightarrow y = \pm x \\ x^2 - y^2 = c > 0 &\Rightarrow \text{hyperbola!} \\ x^2 - y^2 = c < 0 &\Rightarrow \end{aligned}$$



map: (geography)



Example: $f(x, y, z) = x^2 + y^2 - z^2$. $f: \mathbb{R}^3 \rightarrow \mathbb{R}$.

• We cannot draw the graph (need 4 dim).

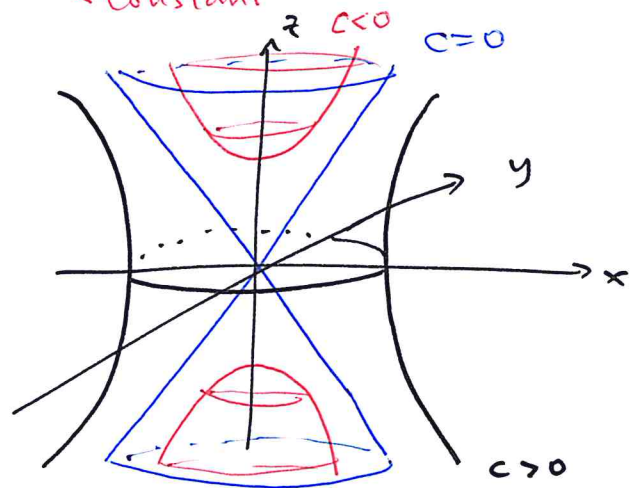
• slice (horizontal)

$f(x, y, z) = c$ — constant 2D surface in \mathbb{R}^3

/ $x^2 + y^2 - z^2 = 0$

— $x^2 + y^2 - z^2 = c > 0$

\ $x^2 + y^2 - z^2 = c < 0$



Generalize: $f(x_1, \dots, x_n)$

level set: $L_c := \{ (x_1, \dots, x_n) \in \Omega \subset \mathbb{R}^n \mid f(x_1, \dots, x_n) = c \}$